



Institut Català
de Nanociència
i Nanotecnologia

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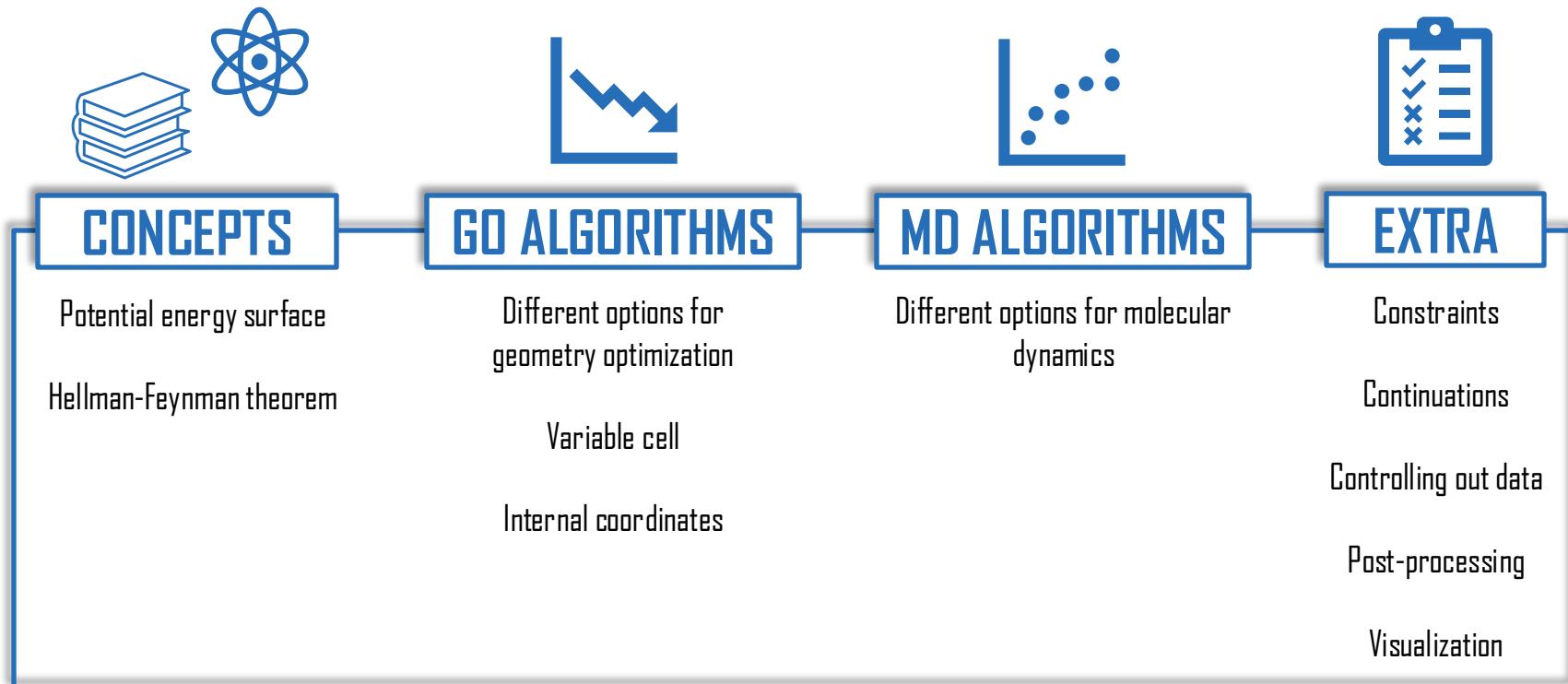
Geometry optimization and molecular dynamics using SIESTA*

Ernane de Freitas Martins

*Based on previous presentations from Emilio Artacho and Marivi Fernandez-Serra, which can be found in the SIESTA webpage

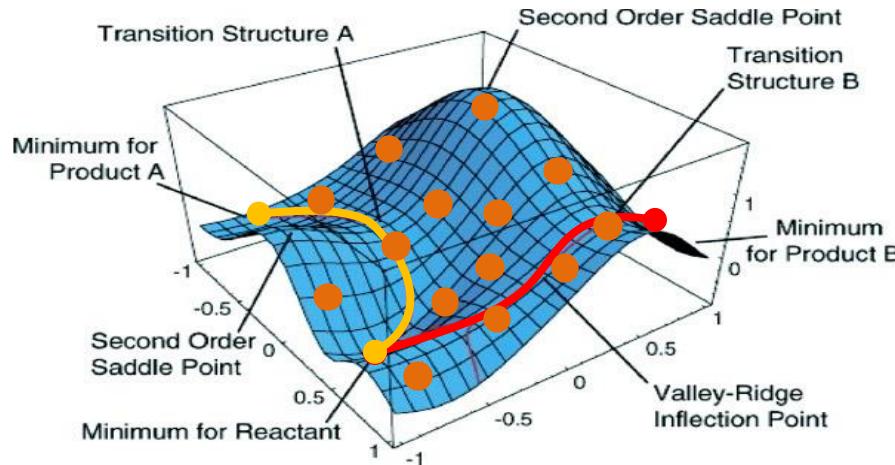
What is this presentation about?

Outline



The potential energy surface - PES

Geometry optimization x molecular dynamics



Reactants $\xrightarrow{TS_A} A$

Reactants $\xrightarrow{TS_B} B$

Geometry optimizations

We move on the PES

Search for local/global minima

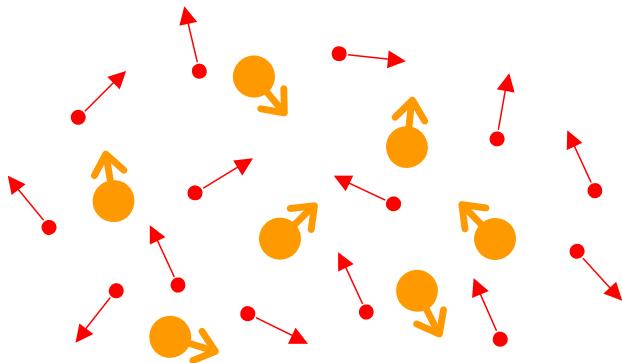
Molecular dynamics

We move over the PES

Sampling

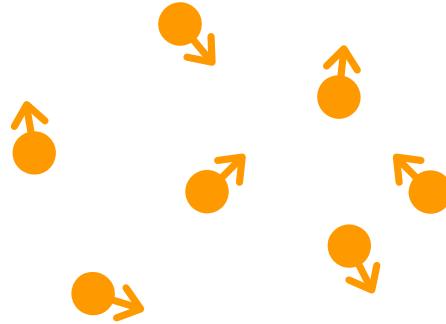
Adiabatic decoupling

Many body problem and how to move atoms



$$\frac{m_n}{m_e} \gg 1$$

Moving atoms



Hellman-Feynman
theorem

Need for computing the \vec{F}

How to compute the forces?

The Hellman-Feynman theorem

$$H(\lambda)$$

Hamiltonian as a function of a continuous parameter

$$|\psi(\lambda)\rangle$$

Eigenvector of $H(\lambda)$ with eigenvalue $E(\lambda)$

$$H(\lambda)|\psi(\lambda)\rangle = E(\lambda)|\psi(\lambda)\rangle$$

Assuming normalized

The Hellman-Feynman theorem

$$\frac{dE}{d\lambda} = \left\langle \psi(\lambda) \left| \frac{dH}{d\lambda} \right| \psi(\lambda) \right\rangle$$

$$\langle \psi(\lambda) | \psi(\lambda) \rangle = 1$$

$$\frac{d}{d\lambda} \langle \psi(\lambda) | \psi(\lambda) \rangle = 0$$

How to compute the forces?

The Hellman-Feynman theorem

- ✓ A proof of concept can be done by writing the energy as $E = \langle \psi(\lambda) | H(\lambda) | \psi(\lambda) \rangle$;
- ✓ Associate parameter λ with the nuclear coordinates R ;
 - ✓ The forces acting on atoms can be calculated as:
$$\checkmark F_i = \nabla_i \varepsilon(R) = \langle \psi_0 | \nabla_i H(R) | \psi_0 \rangle$$

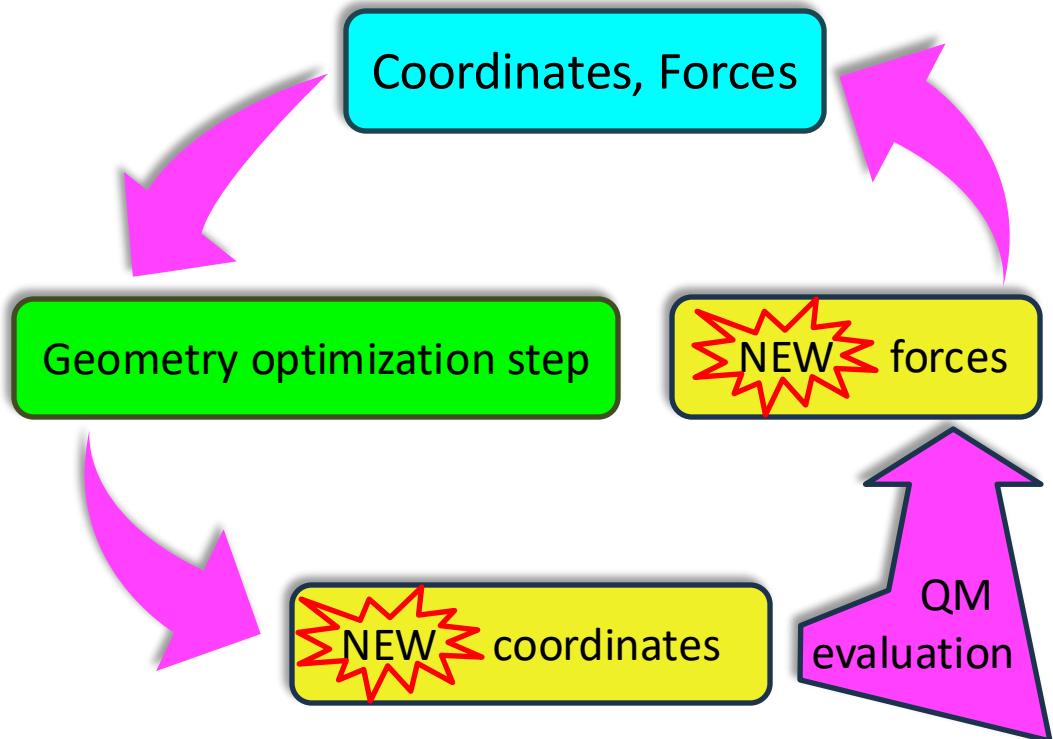
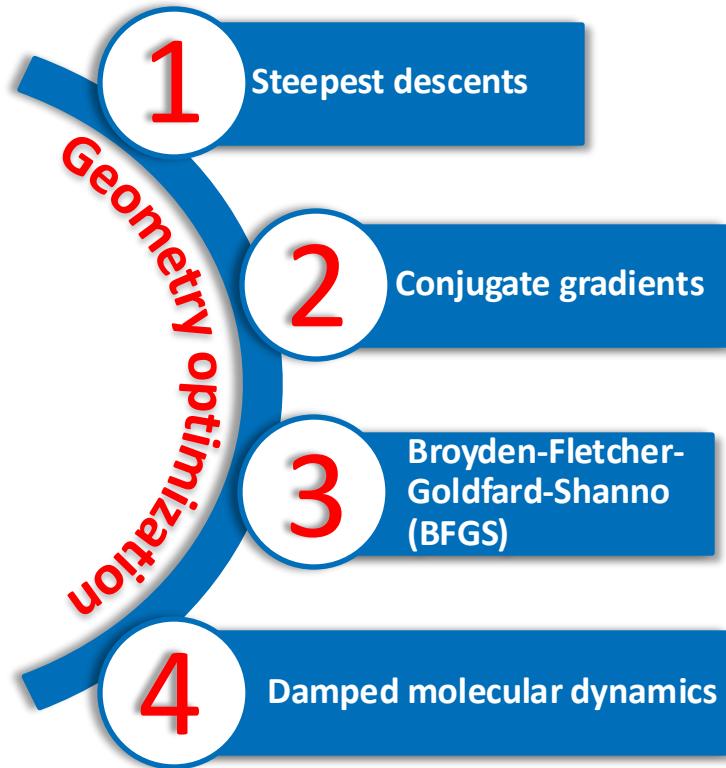
Classical dynamics of ions

using

Ab initio forces

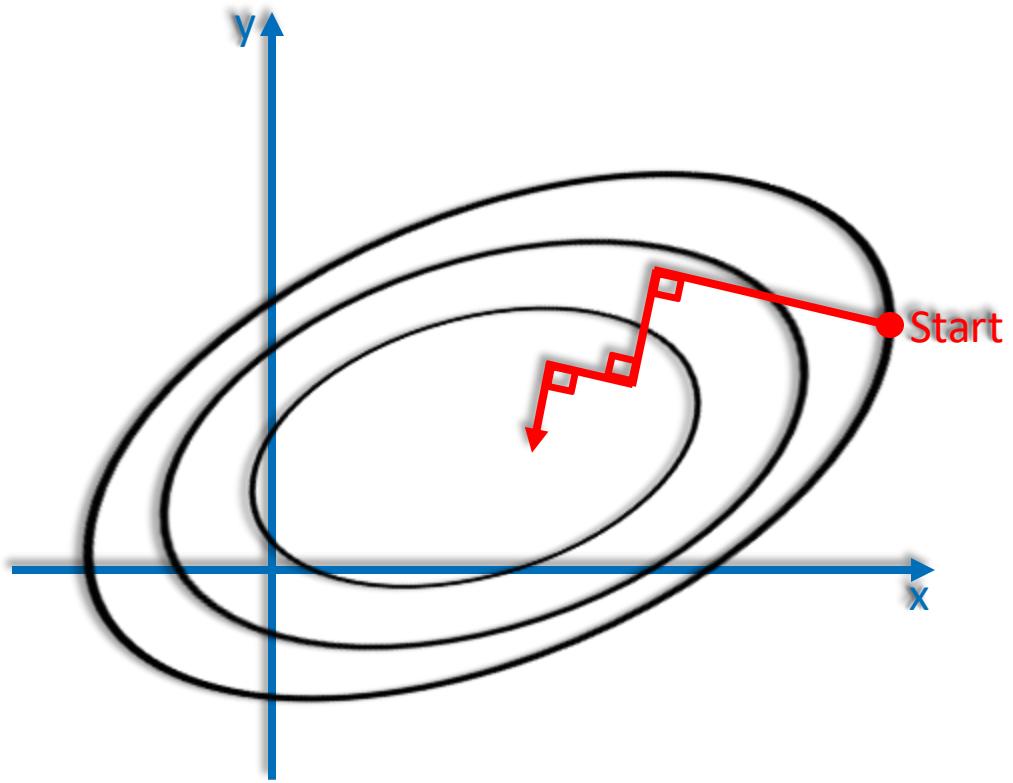
Algorithms to optimize geometries

And more in the manual...



Structural optimization

Steepest descents



The simplest approach, taking a downhill step along the local steepest gradient

Advantages

Simple to implement

Reliable

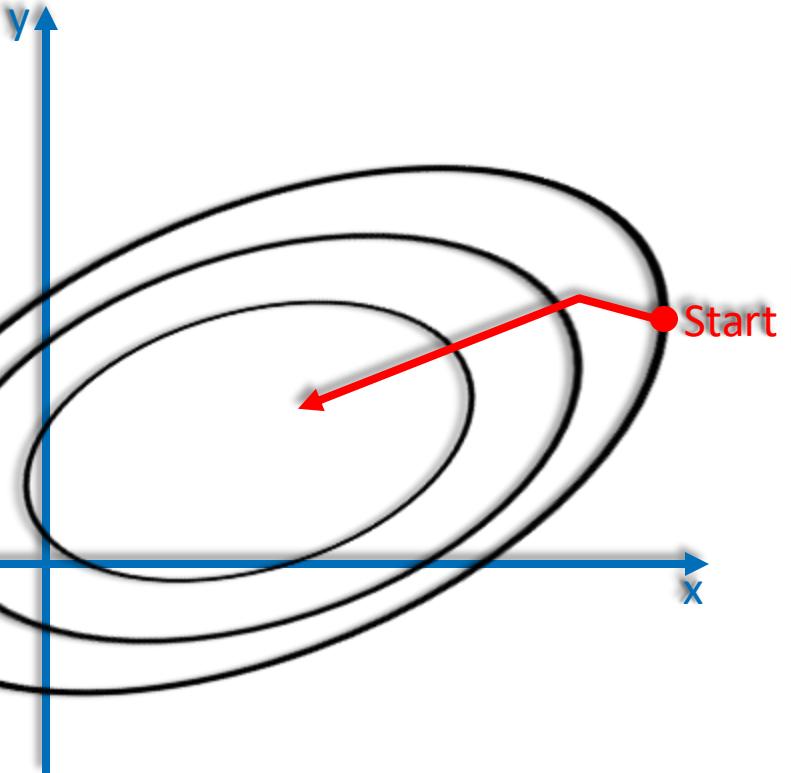
Disadvantages

Slow to converge

Can get stuck in a local minimum

Structural optimization

Conjugate gradients



- Improves steepest;
- Gradient constructed to be conjugate to all previous directions;
- It does not undo the previous minimization;
- It makes a line minimization.

Advantages

Rapid convergence

Low storage requirements

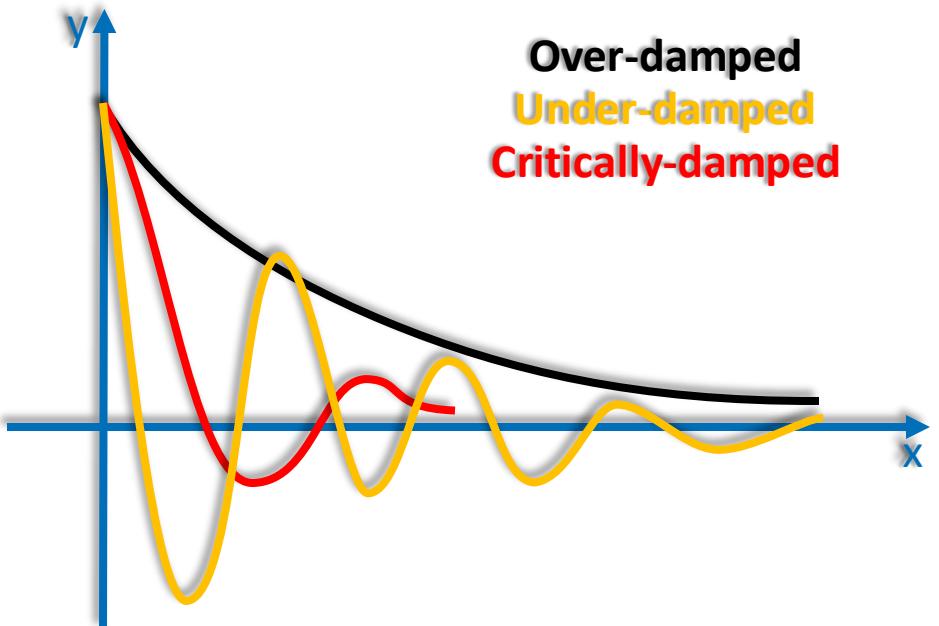
Disadvantages

More complex to implement

Can get stuck in a local minimum

Structural optimization

Damped molecular dynamics



- Improves steepest;
- It uses velocity and forces;
- It starts with $v = 0$ and then adds damping terms to forces: $-\gamma v$;
- It adjusts γ and time step to obtain optimal convergence.

Advantages

Simple to implement

Eventually can escape a local minimum

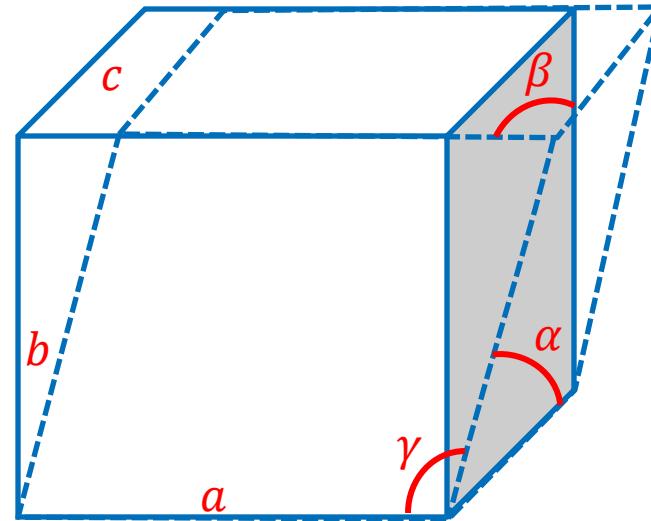
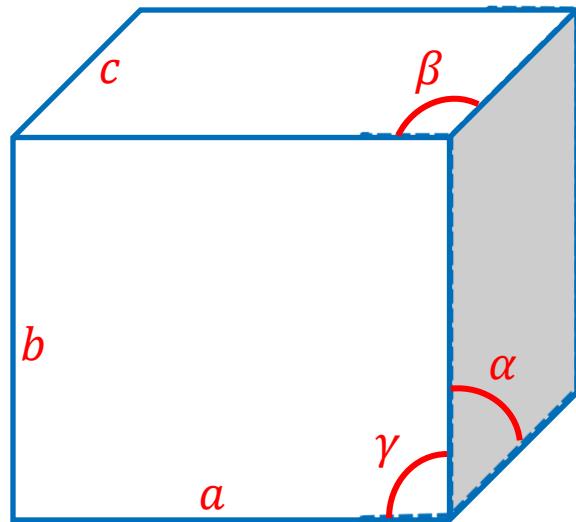
Disadvantages

Convergence rate depends on γ

Can get stuck in a local minimum

Structural optimization

Stress and strain: the cases where the cell is allowed to change



With and without variable cell

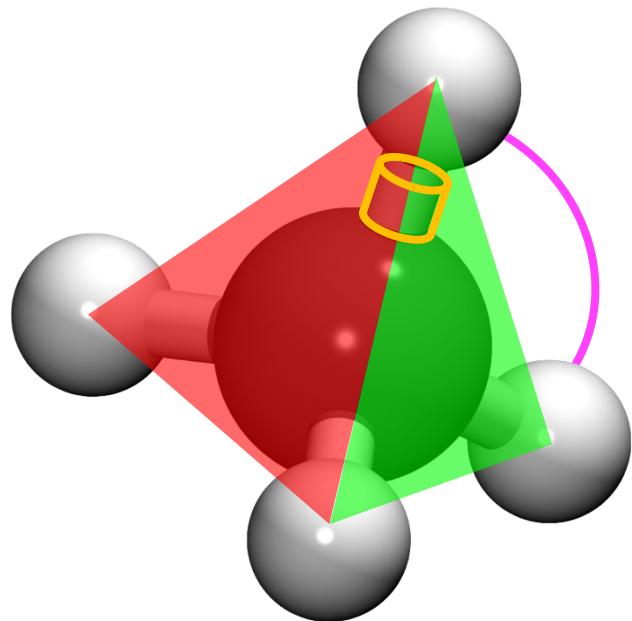
Fixed cell

- Set runtype to conjugate gradients:
 - ***MD.TypeOfRun*** CG, Broyden
- Set maximum number of iterative steps:
 - ***MD.Steps*** 100
- Optionally set force tolerance:
 - ***MD.MaxForceTol*** 0.01 eV/Ang
- Optionally set maximum displacement:
 - ***MD.MaxCGDispl*** 0.2 Bohr

Variable cell

- To allow unit cell to vary:
 - ***MD.VariableCell*** true
- Optionally set stress tolerance:
 - ***MD.MaxStressTol*** 0.1 GPa
- Set an applied pressure:
 - ***MD.TargetPressure*** 1.0 GPa

Z-matrix coordinate format



Use of internal coordinates

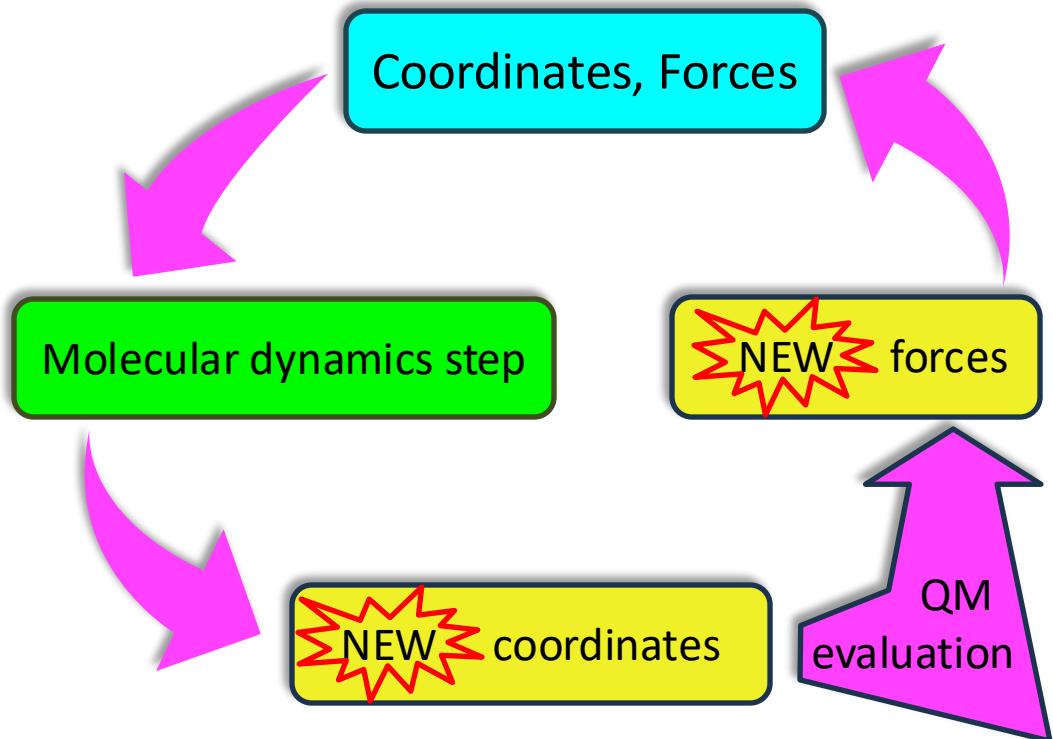
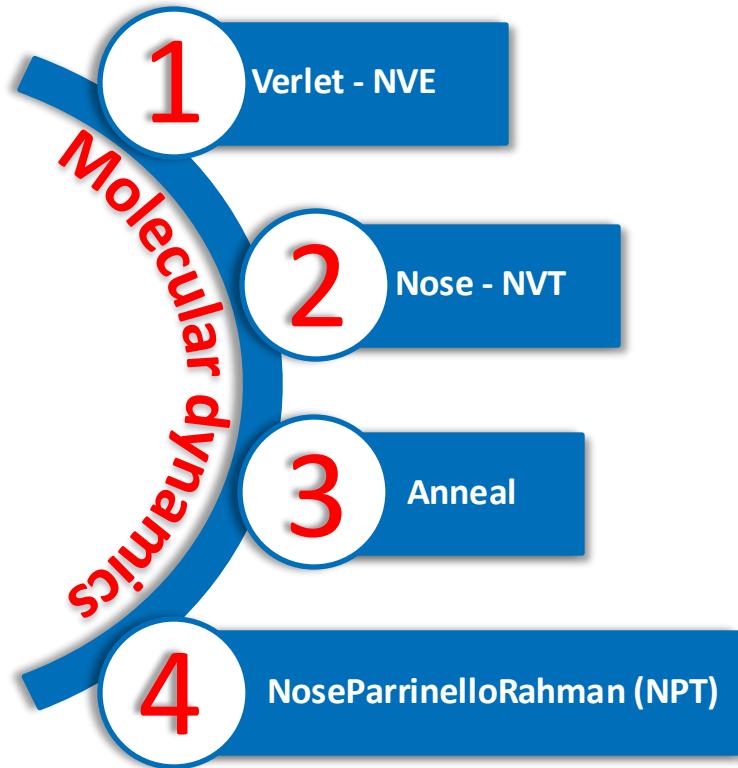
Bond lengths χ_i

Bending angles φ_i

Dihedral angles ξ_i

Algorithms for molecular dynamics

And more in the manual...



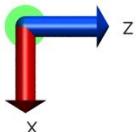
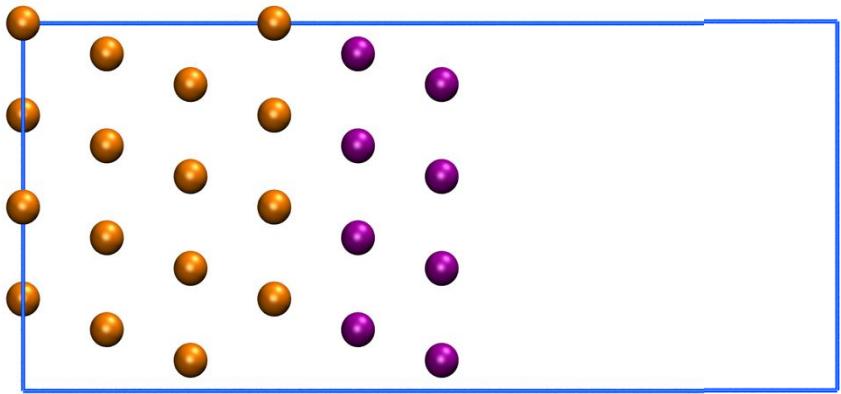
Changes in the input file

*More options in
the manual*

- Set runtype to MD:
 - ***MD.TypeOfRun*** Verlet, Nose, ...
- Set the initial time step:
 - ***MD.InitialTimeStep*** 1
- Set the final time step:
 - ***MD.FinalTimeStep*** 100
- Set the time step:
 - ***MD.LengthTimeStep*** 1 fs
- Set temperature/pressure
 - ***MD.TargetTemperature*** 300 K

Use of constraints

When relevant, one can constrain the movement of atoms



● **Constrained**

● **Free**

```
%block GeometryConstraints
atom Cu
%endblock GeometryConstraints
```

or

```
%block GeometryConstraints
position from 1 to 48
%endblock GeometryConstraints
```

How to continue calculations not finished?

Both geometry optimization and molecular dynamics allow for that

- Files that can be read:
 - *SystemLabel.XV* (vel. and coord.)
 - *SystemLabel.X_RESTART*
 - X is the type of MD
- Manually:
 - Insert the last coordinates;
 - For MD, initial velocities will be generated in this case.
- The *SystemLabel.{ANI,MDE}* will be updated

Make sure files will be read

- *MD.UseSaveXV* true

Controlling output data

Not everything is printed by default...

- Mulliken charges:
 - *WriteMullikenPop* 1
- Charges for MD:
 - *PartialChargesAtEveryGeometry* true
- Electrostatic potential:
 - *SaveElectrostaticPotential* true
- Total potential:
 - *SaveTotalPotential* true
- Coordinate steps:
 - *WriteCoorStep* true

How to post-process data?

Types of post-processing that can be done

- Files:
 - *SystemLabel.MDE*
 - *Temperature, energy...*
 - *SystemLabel.out*
 - *Grep command can be used to extract information to be plotted.*

To plot and generate PNG

Executable

`plot_XXX.sh`



To plot the data of the ***structural optimization*** tutorial:
`plot_enth.sh | plot_stress.sh | plot_constr.sh`

To plot the data of the ***molecular dynamics*** tutorial:
`plot_temp.sh | plot_presure.sh | plot_energies.sh`

How to post-process data?

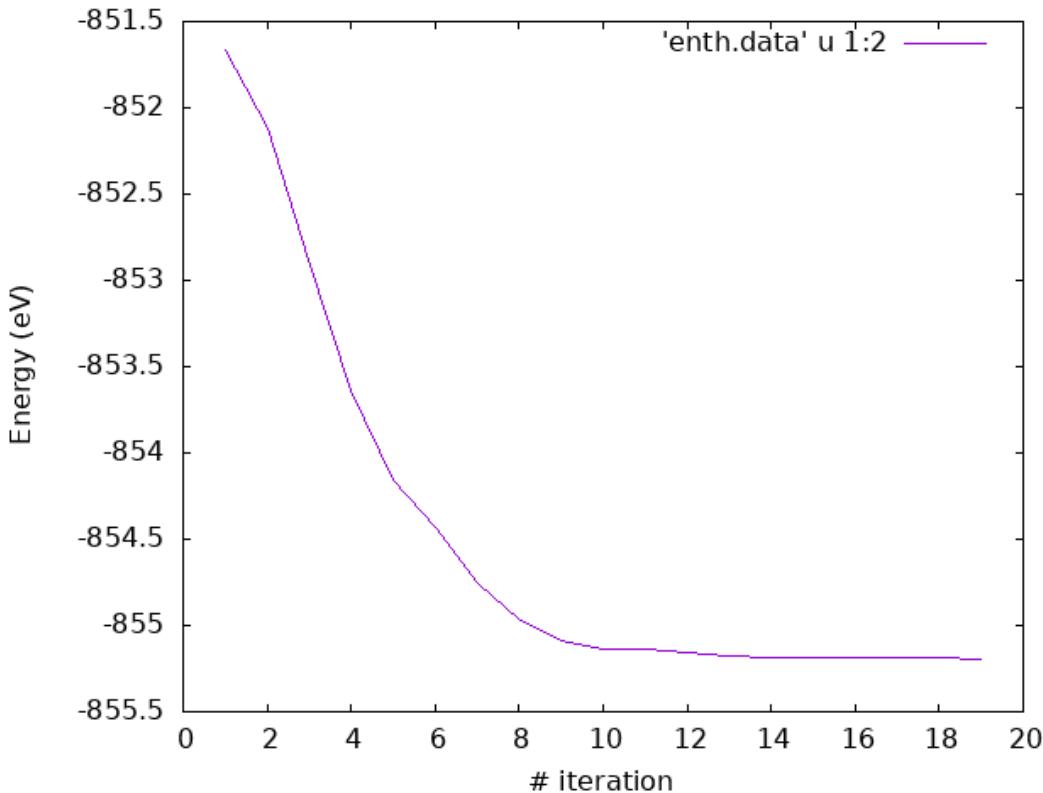
Types of post-processing that can be done

Executable

`plot_enth.sh`

Download
generated png file

Open the png file
on your local
computer



How to visualize trajectories?

Files that can be used for that

ovito SystemLabel.ANI
ovito SystemLabel.xyz
ovito SystemLabel.pdb



- Files:
 - *SystemLabel.ANI*
 - *Coordinates trajectory.*
 - *SystemLabel.STRUCT_OUT*
 - *Last coordinates;*
 - *Need to be converted into PDB:*
 - *ASE, for instance.*

<ase convert SystemLabel.STRUCT_OUT SystemLabel.pdb>

vmd -xyz SystemLabel.ANI
vmd SystemLabel.pdb



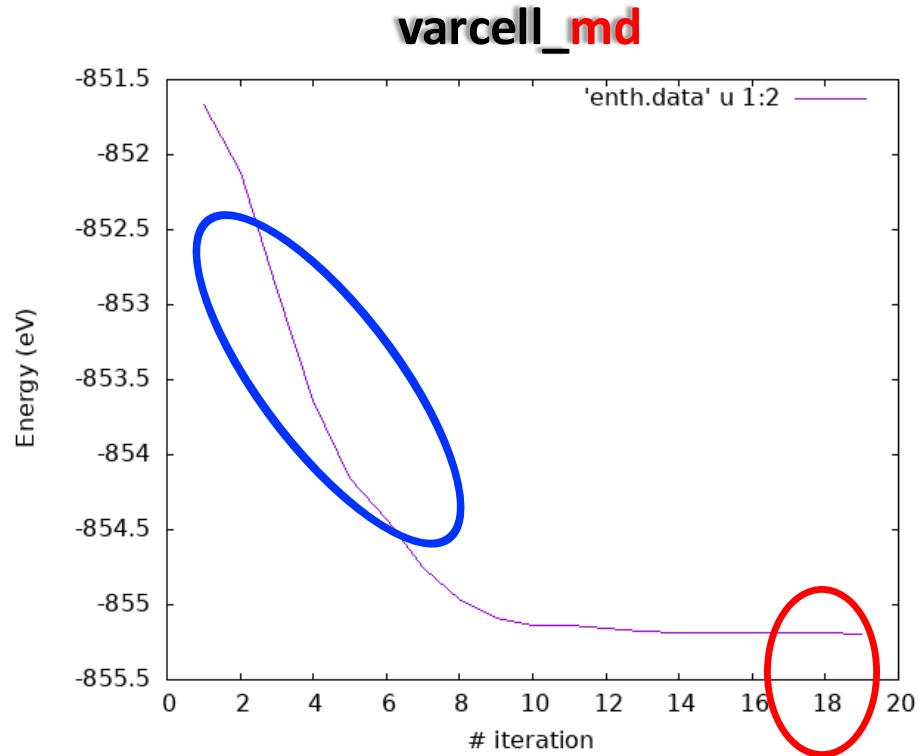
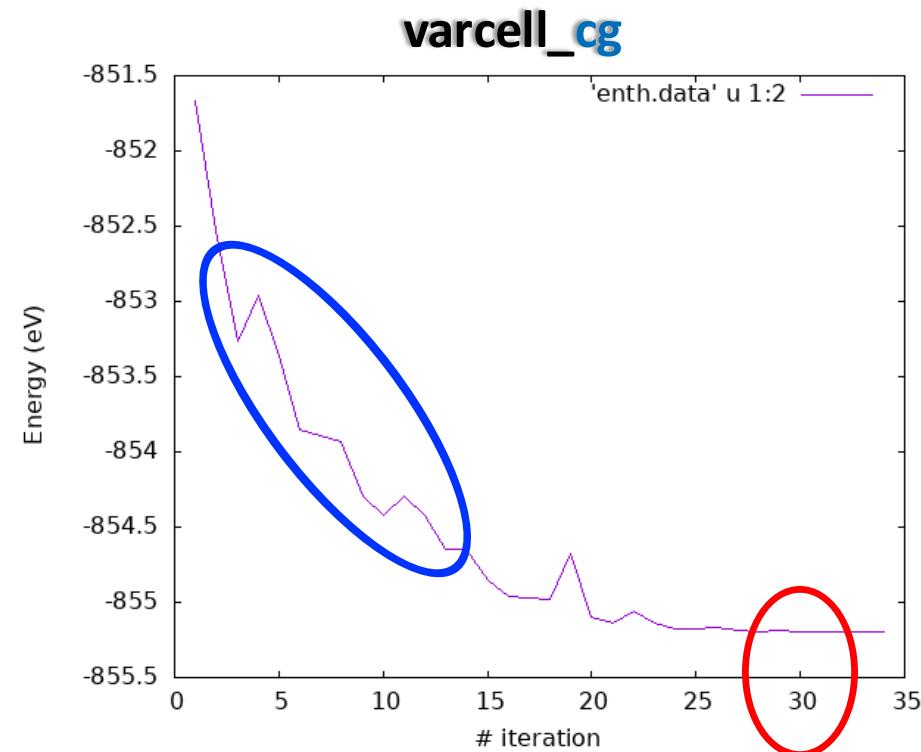
Let's try the tutorials! Questions before?

/gpfs/projects/nct_315/TUTORIALS/day3/01-GeometryOptimization

/gpfs/projects/nct_315/TUTORIALS/day3/02-MolecularDynamics

Some outcomes

Examples of analysis that could be done

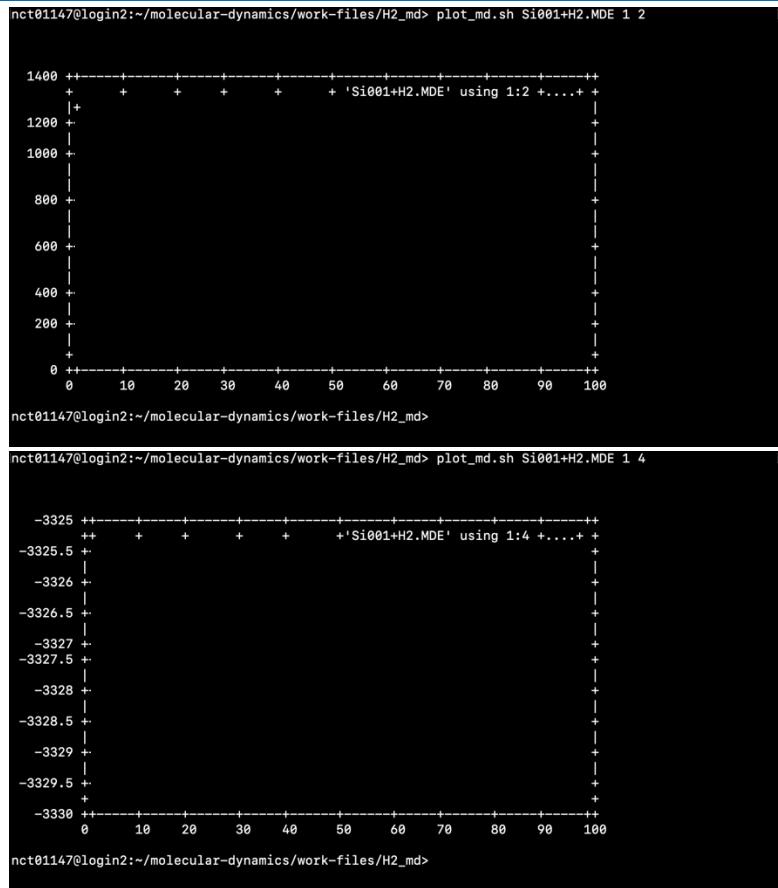
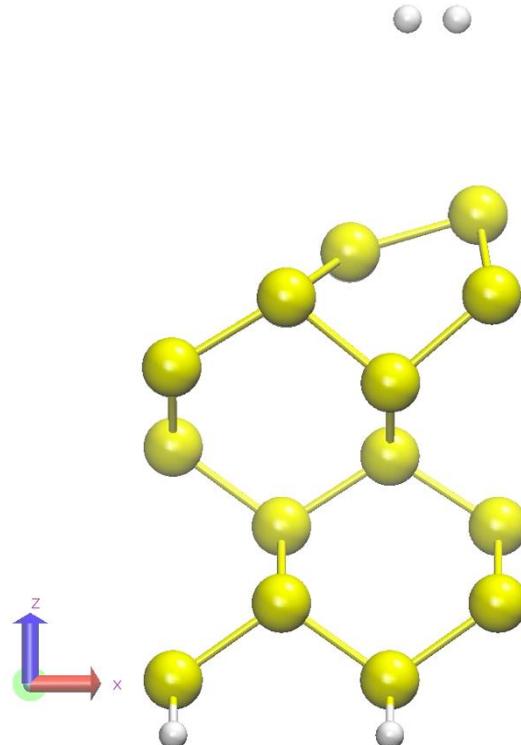


Some outcomes

Examples of analysis that could be done

Some outcomes

Examples of analysis that could be done



The end

That's it!